

Theory and Practice of Differential Entropy Estimation

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- Problem Setup

- Related Works

Theory: Optimal Estimation

- Estimator Construction

- Estimator Analysis

Practice: Adaptive Estimation

- Idea of Nearest Neighbor

- Estimator Analysis

- Numerical Results

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Motivation

Information-theoretic measures:

- ▶ entropy $H(X)$
- ▶ mutual information $I(X; Y)$
- ▶ Kullback–Leibler divergence $D(P\|Q)$

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- ▶ entropy $H(X)$
- ▶ mutual information $I(X; Y)$
- ▶ Kullback–Leibler divergence $D(P\|Q)$

Subroutine for many fields and applications:

- ▶ machine learning: classification, clustering, feature selection
- ▶ causal inference: network flow
- ▶ sociology
- ▶ computational biology
- ▶ ...

Problem Formulation

Problem:

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Choice of Function Class

Hölder ball $\mathcal{H}_d^s(L)$

- ▶ $0 < s \leq 1$: $|f(x) - f(y)| \leq L\|x - y\|^s$
- ▶ $1 < s \leq 2$: $\|\nabla f(x) - \nabla f(y)\| \leq L\|x - y\|^{s-1}$
- ▶ intuition: $\|f^{(s)}\|_\infty \leq L$

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Lipschitz ball (or Besov ball) $\text{Lip}_{p,d}^s(L)$

- ▶ definition: for any $t \in \mathbb{R}^d$,

$$\|f(\cdot + t) + f(\cdot - t) - 2f(\cdot)\|_p \leq L\|t\|^s$$

- ▶ intuition: $\|f^{(s)}\|_p \leq L$

Parameters

Reminder of important parameters:

- ▶ n : sample size
- ▶ d : dimension of support of f
- ▶ $s \in (0, 2]$: smoothness parameter of \mathcal{F}

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Nonparametric Functional Estimation

General Problem

Given $X_1, \dots, X_n \sim f$, we would like to estimate the functional of the form

$$I(f) = \int w(f(x)) dx$$

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Example

- ▶ quadratic functional: $I(f) = \int f(x)^2 dx$
- ▶ cubic functional: $I(f) = \int f(x)^3 dx$

Smooth Functional

- ▶ quadratic functional: elbow effect

Theorem (Bickel–Ritov'88)

$$\inf_{\hat{I}} \sup_{f \in \mathcal{H}_d^s} \mathbb{E}_f |\hat{I} - I(f)| \asymp n^{-\frac{4s}{4s+d}} + n^{-\frac{1}{2}}$$

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- ▶ almost nothing is known for nonsmooth functionals

Differential Entropy Estimation

Kernel-based methods:

- ▶ Joe'89
- ▶ Györfi–van der Meulen'91
- ▶ Hall–Morton'93
- ▶ Paninski–Yajima'08
- ▶ Kandasamy et al.'15
- ▶ ...

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Nearest neighbor methods:

- ▶ Tsybakov–van der Meulen'96
- ▶ Sricharan–Raich–Hero'12
- ▶ Singh–Póczos'16
- ▶ Berrett–Samworth–Yuan'16
- ▶ Delattre–Fournier'17
- ▶ Gao–Oh–Viswanath'17
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Differential Entropy Estimation (Cont'd)

Drawbacks of previous works:

- ▶ **extra assumption**: the density f is lower bounded by a positive universal constant, e.g., $f(x) \geq 0.01$ everywhere

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- ▶ only prove consistency

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Drawbacks of previous works:

- ▶ **extra assumption**: the density f is lower bounded by a positive universal constant, e.g., $f(x) \geq 0.01$ everywhere
- ▶ only prove consistency
- ▶ no new lower bound beyond quadratic case

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Main Result

Theorem

For any d and $p \in [2, \infty)$, $s \in (0, 2]$, we have

$$\inf_{\hat{h}} \sup_{f \in \text{Lip}_{p,d}^s} \mathbb{E}_f |\hat{h} - h(f)| \asymp (n \log n)^{-\frac{s}{s+d}} + n^{-\frac{1}{2}}$$

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Significance

- ▶ first exact expression for the minimax rate, including sharp exponent and exact logarithmic factor

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Significance

- ▶ first exact expression for the minimax rate, including sharp exponent and exact logarithmic factor
- ▶ parametric rate $n^{-\frac{1}{2}}$ requires $s \geq d$
- ▶ does not use any extra assumption (e.g., boundedness of f)
- ▶ improves the best known lower bound

Idea: Two-stage Approximation

Recall

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- ▶ involves both **function** $f(x)$ and **functional** $y \mapsto -y \log y$

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- ▶ can estimate $-f(x) \log f(x)$ for every x and then integrate
- ▶ involves both **function** $f(x)$ and **functional** $y \mapsto -y \log y$
- ▶ two-stage approximation: first approximate the **function** and then approximate the **functional**

First Stage

How to estimate $f(x)$ at a given x ?

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Example

When $K_h(x) = \frac{1}{2h} \mathbb{1}_{[-h,h]}(x)$, we have

$$f_h(x) = \frac{1}{2h} \int_{x-h}^{x+h} f(y) dy$$

First Stage (Cont'd)

Advantages of f_h :

- ▶ close to f for small bandwidth: $\|f_h - f\|_p \lesssim h^s$

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First-stage approximation

Estimate $h(f_h)$ instead of $h(f)$!

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U-statistics

$$U_k(x) = \frac{1}{\binom{n}{k}} \sum_{1 \leq i_1 < i_2 < \cdots < i_k \leq n} \prod_{j=1}^k K_h(x - X_{i_j})$$

- ▶ efficiently computable via Newton's identity

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Second-stage Approximation

Write the objective functional as

$$-f_h(x) \log f_h(x) \approx \sum_{k=0}^K a_k f_h(x)^k$$

then $\hat{H}(x) = \sum_{k=0}^K a_k U_k(x)$ is an unbiased estimator for the polynomial approximation.

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- ▶ integrate the pointwise estimate

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Error Decomposition

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Error Decomposition

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 &= \text{approx. error} + \text{bias} + \text{std} \\
 &\lesssim h^s + \frac{\log n}{nh^d K^2} + \frac{2^K}{n\sqrt{h^d}}
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 \end{aligned}$$

Choosing $h \asymp (n \log n)^{-\frac{1}{s+d}}$, $K \asymp \log n$ completes the proof.

Key Lemma in Bounding $|h(f_h) - h(f)|$

Inequality of Fisher Information

Let $f \in C^2(\mathbb{R})$ be supported on $[0, 1]$, and $f \geq 0$ everywhere. The following inequality holds:

$$J(f) \triangleq \int \frac{(f')^2}{f} \leq C_p \|f''\|_p$$

where $1 < p \leq \infty$.

Proof of Key Lemma

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Rearranging:

$$|f'(x)| \leq \inf_{h>0} \left[\frac{2f(x)}{h} + 2h \cdot \frac{1}{2h} \int_{x-h}^{x+h} |f''(y)| dy \right]$$

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$$0 \leq f(x-h) \leq f(x) - hf'(x) + h \int_{x-h}^x |f''(y)| dy$$

Rearranging:

$$|f'(x)| \leq \inf_{h>0} \left[\frac{2f(x)}{h} + 2h \cdot \frac{1}{2h} \int_{x-h}^{x+h} |f''(y)| dy \right]$$

$$\leq \inf_{h>0} \left[\frac{2f(x)}{h} + 2h \cdot \sup_{r>0} \frac{1}{2r} \int_{x-r}^{x+r} |f''(y)| dy \right]$$

Proof of Key Lemma

Non-negativity of f :

$$0 \leq f(x+h) \leq f(x) + hf'(x) + h \int_x^{x+h} |f''(y)| dy$$

$$0 \leq f(x-h) \leq f(x) - hf'(x) + h \int_{x-h}^x |f''(y)| dy$$

Rearranging:

$$|f'(x)| \leq \inf_{h>0} \left[\frac{2f(x)}{h} + 2h \cdot \frac{1}{2h} \int_{x-h}^{x+h} |f''(y)| dy \right]$$

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$$= 2\sqrt{f(x)M[|f''|](x)}$$

Maximal Function

Definition (Hardy–Littlewood Maximal Function)

For non-negative function h , the Hardy–Littlewood maximal function $M[h]$ is defined as

$$M[h](x) \triangleq \sup_{r>0} \frac{1}{|B(x; r)|} \int_{B(x; r)} h(y) dy.$$

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Theorem (Hardy–Littlewood Maximal Inequality)

The following tail bound holds:

$$\text{Vol} \left\{ x \in \mathbb{R}^d : M[h](x) > t \right\} \leq \frac{C_d}{t} \int h(x) dx.$$

Consequently, $\|M[h]\|_p \leq C_p \|h\|_p$ for any $p \in (1, \infty]$.

Proof of Key Lemma (Cont'd)

Recall

$$|f'(x)| \leq 2\sqrt{f(x)M[|f''|](x)}.$$

Proof of Key Lemma (Cont'd)

Recall

$$|f'(x)| \leq 2\sqrt{f(x)M[|f''|](x)}.$$

Consequently,

$$\int \frac{(f')^2}{f} \leq 4\|M[f'']\|_1 \leq 4\|M[f'']\|_p \leq 4C_p\|f''\|_p.$$

Applications of Maximal Function

- ▶ Doob's martingale inequality
- ▶ Lebesgue differentiation theorem
- ▶ Birkhoff's pointwise ergodic theorem

Summary

- ▶ two-stage approximation is optimal for differential entropy estimation
- ▶ polynomial-time estimator
- ▶ need to tune parameters h, K in practice
- ▶ requires the knowledge of s

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Another View of Differential Entropy

$$h(f) = \int -f(x) \log f(x) dx$$

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Question

How to find a good estimator $\hat{f}(X_i)$?

Nearest Neighbor Estimator

Let h_i be the distance of X_i to its nearest neighbor, we set

$$\hat{f}(X_i) \cdot \text{Vol}(B(X_i; h_i)) = \frac{1}{n}.$$

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Kozachenko–Leonenko (KL) Nearest Neighbor Estimator

$$\hat{h}_{\text{KL}} = \frac{1}{n} \sum_{i=1}^n \log [n \text{Vol}(B(X_i; h_i))] + \gamma$$

where $\gamma \approx 0.577$ is Euler's constant.

Insights behind KL Estimator

Key Observation

For each i , $\int_{B(x_i, h_i)} f(y) dy \sim \text{Beta}(1, n - 1)$.

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we have

$$\mathbb{E}_f[\hat{h}_{\text{KL}}] - h(f) = \mathbb{E}_f \left[\log \frac{f(X)}{f_h(X)(X)} \right] + \underbrace{\mathbb{E} \log[n \cdot \text{Beta}(1, n - 1)] + \gamma}_{=O(n^{-1})}$$

Main Result

Theorem

For any $d > 0$ and $s \in (0, 2]$, the KL estimator satisfies

$$\sup_{f \in \mathcal{H}_d^s} \mathbb{E}_f |\hat{h}_{\text{KL}} - h(f)| \lesssim n^{-\frac{s}{s+d}} \log n + n^{-\frac{1}{2}}$$

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Significance

- ▶ optimal up to logarithmic factor
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- ▶ **adaptive** in smoothness s
- ▶ do not need to tune parameter

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Question

For small $\varepsilon > 0$, find a good upper bound of

$$\mathbb{E} \left[\int f(x) \mathbb{1}(f_{h(x)}(x) \leq \varepsilon) dx \right]$$

Minimal Function

Definition (Minimal Function)

For non-negative function f supported on $[0, 1]^d$, the minimal function $m[f]$ is defined as

$$m[f](x) = \inf_{0 < r \leq 1} \frac{1}{|\text{Vol}(B(x; r))|} \int_{B(x; r)} f(y) dy.$$

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Observation

$$\mathbb{E} \left[\int f(x) \mathbb{1}(f_{h(x)}(x) \leq \varepsilon) dx \right] \leq \int f(x) \mathbb{1}(m[f](x) \leq \varepsilon) dx$$

Generalized Maximal Inequality

Theorem (Generalized Maximal Inequality)

Let μ_1, μ_2 be two Borel measures on metric space $\Omega \subset \mathbb{R}^d$, then for any $t > 0$,

$$\mu_2 \left\{ x \in \Omega : \sup_{r>0} \frac{\mu_1(B(x; r))}{\mu_2(B(x; r))} > t \right\} \leq \frac{C_d}{t} \cdot \mu_1(\Omega).$$

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Corollary

Choose $\mu_1 =$ Lebesgue measure, $\frac{d\mu_2}{d\mu_1} = f$, we have

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$$\begin{aligned} \int f(x) \mathbb{1}(m[f](x) \leq \varepsilon) dx &\leq \mu_2 \left\{ x \in [0, 1]^d : \sup_{r>0} \frac{\mu_1(B(x; r))}{\mu_2(B(x; r))} > \frac{1}{\varepsilon} \right\} \\ &\leq C_d \cdot \varepsilon. \end{aligned}$$

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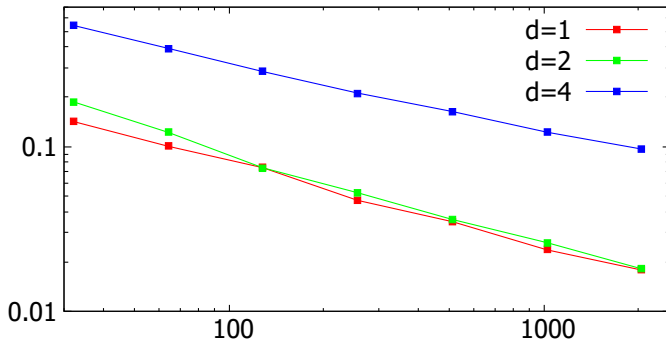
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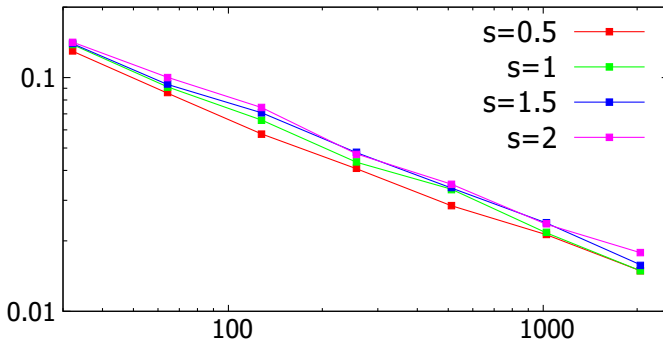
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Dimensionality d $k = 5, s = 2$ 

Smoothness s

$k = 5, d = 1$



Conclusion

Take-home message:

- ▶ two-stage approximation (first approximate the function, then approximate the functional) is optimal
- ▶ nearest neighbor estimator is near-optimal and adaptive to the smoothness parameter
- ▶ Hardy–Littlewood maximal inequality is crucial to deal with density close to zero

References

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- ▶ Jiantao Jiao, Weihao Gao, and Yanjun Han, “The Nearest Neighbor Information Estimator is Adaptively Near Minimax Rate-Optimal”, *arXiv preprint, arXiv:1711.08824*.